# NATIONAL INSTITUTE OF TECHNOLOGY KARNATAKA, SURATHKAL

DEPARTMENT OF MECHANICAL ENGINEERING POST SRINIVASNAGAR, MANGALORE – 575 025 (D K)

Phone: (0824) 2474000. Fax: (0824) 2474033

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### **NOTICE INVITING QUOTATION**

Notification. No: NITK/ME/SC/CSP/04 dated: 2/03/2023

Name of Goods	Customized Solar panel with inner re-volute controller mechanism
Estimated Amount:	₹ 2 lakhs
Time for Supply of item after release of Purchase order	7 (Days)
Document Download / Sale Start Date	2/03/2023
Clarification Start Date	2/03/2023
Clarification End Date	4/03/2023
Bid Submission Start Date	2/03/2023
Last Date for submission of bids	11/03/2023 before 3.00 PM
Bid Opening Date	13/03/2023 before 3.00 PM
Address for Submission of bids	Dr. Saurabh Chandraker
	Assistant Professor
	Dept. of Mechanical Engineering, National Institute of
	Technology Karnataka Surathkal, Mangalore - 575 025
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#### **NOTICE INVITING QUOTATION (NIQ)**

The National Institute of Technology Karnataka, Surathkal (in short – NITK, Surathkal) is an Institute Of National Importance Under Ministry of Education Govt of India, imparting Technical Education and engaged in Research Activities. It is proposed to procure the items for the departmental academic/research activities.

Sealed Quotations as per the Price Schedule given in this NIQ are invited for the following items subject to the terms and conditions, from the reputed manufacturers or its authorised dealers so as to reach on or before scheduled date and time. The quotations in the firm's Business letter head should be address to the "Director, NITK, Surathkal". The envelope shall be superscribed with the Quotation Notification Number and the Name of the Goods for which quotation is submitted.

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Bid Opening Date	13/03/2023 before 3.00 PM

Sd/-**HOD** 

Note: Institute shall not be responsible for any postal delay about non-receipt /non-delivery of the bids or due to wrong addressee.

### SECTION-1 Terms and Conditions

- 1. The rates should be quoted for preferably FOR destination from supply within India.
- 2. The bidder shall indicate the excise duty exemption for the goods if applicable.
- The rate quoted should be on unit basis. Taxes and other charges should be quoted separately, considering exemptions if any. The rate should be quoted in INR only
- 4. Rate quoted should be inclusive of Testing, commissioning and Installation of equipment and Training.
- 5. Payment: No advance payment will be made. Payment will be made only after the supply of the item in good and satisfactory condition and receipt of performance security by supplier.
- 6. Guarantee/Warrantee period should be specified for the complete period should be specified in section 3 of this tender document.
- Period requirement for the supply and installation of item should be specified in section 3 of this tender document.
- 8. In case of dispute, the matter will be subject to Mangalore Jurisdiction only.

#### **SECTION-2** SCHEDULE OF REQUIREMENTS, SPECIFICATIONS AND ALLIED DETAILS

[ To be filled up by the Department / Centre of NITK, Surathkal ]

Item(s) Name to be Procured : Customized Solar panel with inner re-volute controller mechanism

Brief Specifications of the Item(s) (Attach Additional Sheet if necessary) : Detailed Specification is attached below in Annexure-1

Quantity

: 3 panel, 1 mechanism and 1 controller

Any other details / requirement

Warranty Period required : 2 yr

Delivery Schedule expected after placement of Purchase order

(in Weeks) : 7 days

# SECTION 3 PRICE SCHEDULE

[ To be used by the bidder for submission of the quotation]

1.	Item Name	:	
2.	Specifications (Conforming to Schedule of requirements Enclose additional sheets if necessary)	:	
3.	Currency and Unit Price	:	
4.	Quantity	:	
5.	Item Cost (SI No. 3 * SI. No. 4 )	:	
6.	<ul><li>Taxes and Other Charges</li><li>(i) Specify the type of taxes and duties in percentages and also in figures.</li><li>(ii) Specify Other Charges in figures.</li></ul>	:	
7.	Warranty Period (Conforming to the Schedule of requirements)	:	
8.	Delivery Schedule (Conforming to the Schedule of requirements)	:	
9.	Name and address of the Firm for placing purchase order	:	
10.	Name and address of Indian authorized agent ( in case of imports only)	:	
Signat	ure of the Bidder:		
Name	and Designation:		
Busine	ess Address :		
Place: Date:		Seal of the E	Bidder's Firm

# SECTION 4 CONTRACT FORM

[ To be provided by the bidder in the business letter head]

- 1. (Name of the Supplier's Firm) hereby abide by the delivery schedule mentioned in this document for supply of the items if the purchase order is awarded.
- 2. The item will be supplied conforming to the specifications stated in this document without any defect and deviations.
- 3. Warranty will be given for the period mentioned in this document and service will be rendered to the satisfaction of NITK, Surathkal during this period.

Signature of the Bidd	er:	
Name	:	
Business Address	:	
Place : Date :		Seal of the Bidder's Firm

#### **Annexure-1**

### **Specification Details**

### Introduction:-

Design and modelling of Customized Solar panel with inner re-volute controller mechanism & having an opening and closing mechanism (Due to rotatory motion of shaft), other product details shown below.

### **Product Details**

- Customized Solar Panel opening & closing mechanism parts are divided in to three parts. Total number of plates are nine, having circular groove connecting continuously to each other, while revolving get open and close vise versa, in hollow shaft having path for connecting wires from PN junction. (Note:- All dimensions is in millimeters)
- 1. Solar Panel Layers
- 2. Solar Panel Shape, Size & material
- 3. Re volute joints
- 4. Shaft
- 5. Balls

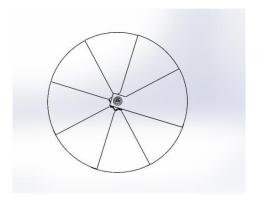
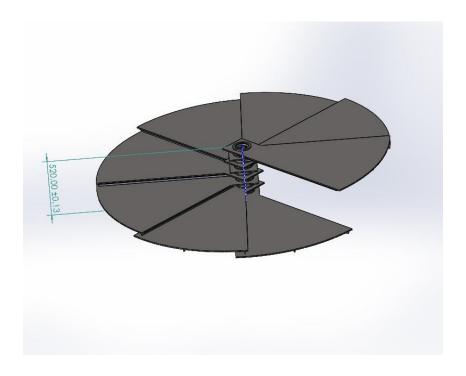


Figure:- Top View



Figure:- Front View



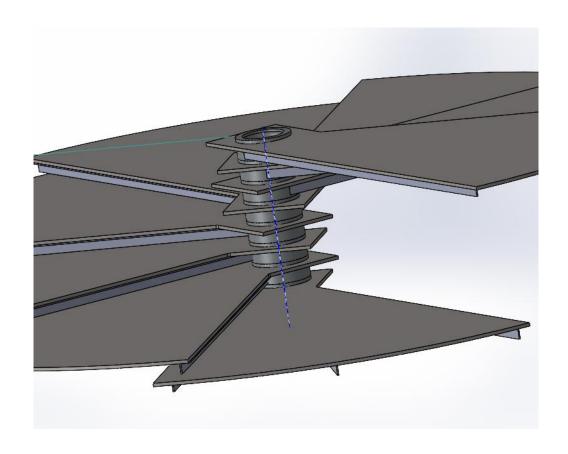


Figure:- Isometric view

Mass Properties of Product		
Sl no.	Properties	Values
1	Mass (g)	176542.06 Grams
2	Volume (mm <sup>3</sup> )	0.079207981.31 m <sup>3</sup>
3	Surface area $(mm^2)$	18.034974 m^2
4	Elements	1,Solar Plate 2,Shaft 3, Re volute 4, Balls
5	No. Of Solar Plates required	3
6	Centre of mass (mm)	X = 33 Y = 934 Z = 930
7	Principal axes of inertia and principal moments of inertia taken at the centre of $mass (g \times mm^2)$	Ix = (0.64, 0.75, 0.16) Px = 48776547852.74 Iy = (-0.76, 0.65, 0.00) Py = 50009347310.31 Iz = (-0.11, -0.12, 0.99) Pz = 94437327909.33
8	Moments of inertia taken at the centre of mass and aligned with the output coordinate system ( $g \times mm^2$ )	Lxx = 50009347310.31 Lxy = 0.00Lxz = 4833055069.64 Lyx = 0.00 Lyy = 50009347310.31 Lyz = 5604673860.03 Lzx = 4833055069.64 Lzy = 5604673860.03 Lzz = 93204528451.76
9	Moments of inertia taken at the output coordinate system $(g \times mm^2)$	Ixx = 356953905046.68 lxy = 5499651889.76lxz = 10307187212.46 lyx = 5499651889.76lyy = 202963991210.92 lyz = 159075292768.69 lzx = 10307187212.46 lzy = 159075292768.69 lzz = 247586775639.63

### 1) Solar Panel Layers

Customize solar panel having combination of different layering materials.

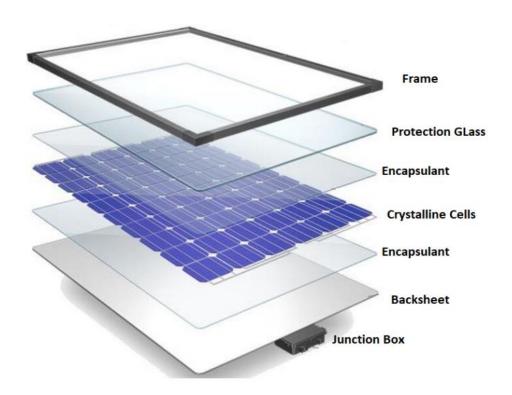


Figure:- Layers of PV Module

Layer of PV Module		
S No.	Layer Name	Description
1	Frame	Aluminium
2	Protecting glass	Ethylene Vinyl Acetate
3	Crystalline Cells	Mono crystalline Solar Panel
4	Back sheet	Carbon Fiber
5	Junction Box	IP68, 3 Bypass Diodes

Slotted solar power description		
SI No.	o. Specification Value	
1	Diameter of circular panel	2.808 m
2	Thickness of circular panel	0.04 m
3	Surface Area of circular panel	$1.68 m^2$
4	Volume of circular panel	$0.0818  m^3$
5	Weight of Circular panel for above configuration 14.565 Kg	
6	1 Solar Cell power 4.5 watts	
7	Number of solar cells used in single plate in circular panel 30	
8	Total number of plates use in System	2
9	Total Number of solar cells used in model $30 \times 2=60$	
10	Total maximum power output (watts ) $60 \times 4.5 = 270$ Watts	
12	Estimate Efficiency of Circular panel for above configuration	19%

Hexcel AS4C(carbon Fiber)		
S. No. Properties Values		Values
1	Density	1.78 g/cc
2	Tensile Modulus	231 G Pa
3	Tensile Strength at Break	4654 M Pa
4	Elongation at Break	1.8%

<b>Aluminium 70</b>	75 T6 Properties	
S. No.	Properties	Values
1	Density	2810 <b>g/mm³</b>
2	Young's modulus (E)	$71700  N/mm^2$
3	Tensile Strength ( $\sigma_t$ )	572 <b>N/mm²</b>
4	Elongation ( $\epsilon$ ) at break	11%
5	Poisson's ratio	0.33
6	Hardness Rockwell	87 HRB

### Single Solar plate

Mass Properties of Single Plate		
S No.	Properties	Values
1	Mass (g)	14.565 Kg
2	Volume (mm <sup>3</sup> )	8182781.41 cubic millimeters
3	Surface area (mm <sup>2</sup> )	1682850.16 square millimeters
4	Thickness	40mm
	Material	Hexcel AS4C(carbon Fiber)
5	Outer Diameter	2808mm
6	Centre of mass (mm)	X = 734.63 Y = -242.52 Z = 5.00
7	Principal axes of inertia and principal moments of inertia taken at the centre of mass $(g \times mm^2)$	Ix = (0.92, -0.40, 0.00) Px = 733876792.41 Iy = (0.40, 0.92, 0.00) Py = 1700444261.73 Iz = (0.00, 0.00, 1.00) Pz = 2434078298.29
8	Moments of inertia taken at the centre of mass and aligned with the output coordinate system ( $g \times mm^2$ )	Lxx = 885069041.65 Lxy = -351110258.32 Lxz = 0.00 Lyx = -351110258.32 Lyy = 1549252012.49Lyz = 0.00 Lzx = 0.00Lzy = 0.00Lzz = 2434078298.29
9	Moments of inertia taken at the output coordinate system $(g \times mm^2)$	lxx = 1742106405.03lxy = -2946115017.19 lxz = 53500894.24 lyx = -2946115017.19 lyy = 9410314328.21lyz = -17661926.71 lzx = 53500894.24 lzy = -17661926.71 lzz = 11151449709.85

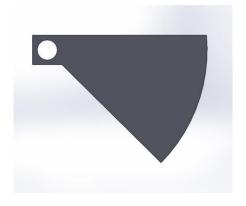


Figure:- Front view of Plate

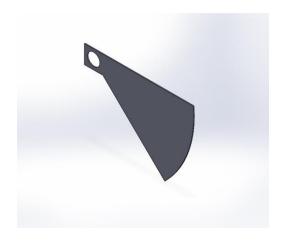


Figure:- Isometric view of Plate

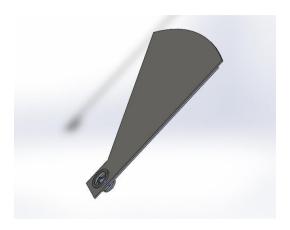


Figure:- Assembly with Re volute joint & Plate

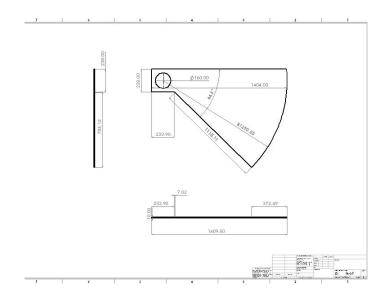
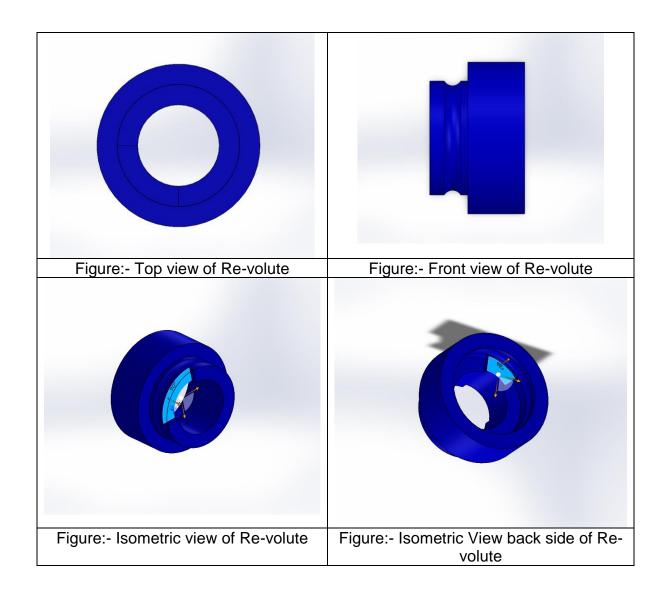
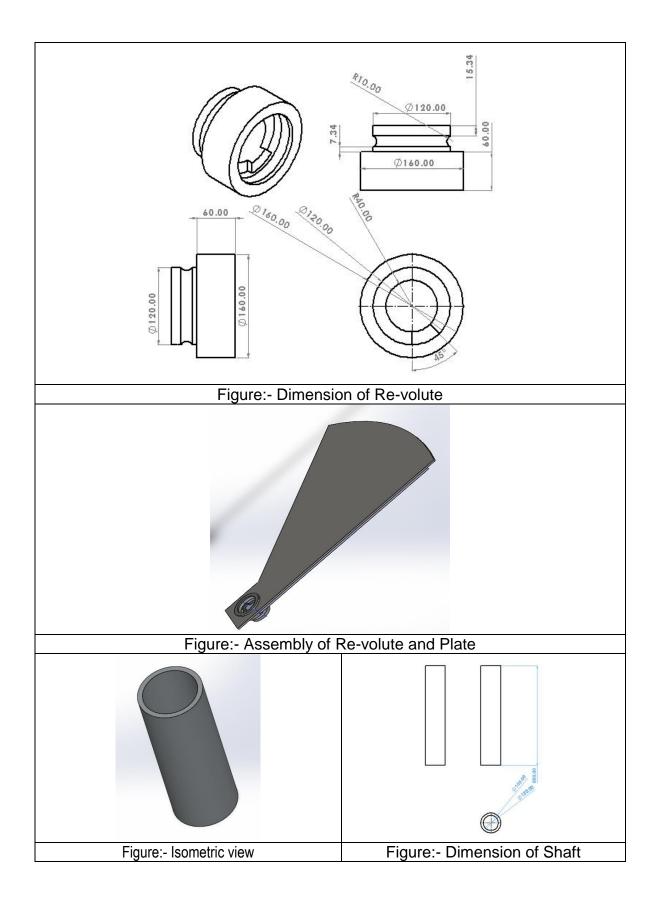


Figure:- Dimensions of Plate

### Re volute

S. No.	Property	Specification
1	Material	Chrome Stainless Steel
2	Mass	6.634 Kg
3	Volume	850616 cubic millimeters
4	Surface area	107361 square millimeters
5	Center of mass	X= -5.76, Y=0.17, Z=0.42
6	Mass Density	7800 Kg/m^3
7	Elastic Modulus	2e+11 N/m^2
8	Yield Strength	172339000 N/m^2
9	Poisson's Ratio	0.28
10	Shear Modulus	7.7e+10 N/m^2
11	Length of Shaft	800mm
12	Outer Diameter	160mm
13	Inner Diameter	120mm
14	Principal axes of inertia and principal moments of inertia taken at the centre of mass $(g \times mm^2)$	Ix = (-0.01, 0.93, -0.36) Px = 17552766.74 Iy = (-0.03, 0.36, 0.93) Py = 17691078.83 Iz = (1.00, 0.02, 0.02) Pz = 26771924.00
15	Moments of inertia taken at the centre of mass and aligned with the output coordinate system $(g \times mm^2)$	Lxx = 26761663.47 Lxy = -224666.89 Lxz = - 207055.53 Lyx = -224666.89 Lyy = 17575865.52 Lyz = - 51187.53 Lzx = -207055.53 Lzy = -51187.53 Lzz = 17678240.58
16	Moments of inertia taken at the output coordinate system $(g \times mm^2)$	lxx = 26763042.40 lxy = -231332.43 lxz = - 223147.57 lyx = -231332.43 lyy = 17797054.53 lyz = - 50700.00 lzx = -223147.57 lzy = -50700.00 lzz = 17898454.53





### **Shaft Dimensions**

T. No.	Property	Specification
1	Material	Chrome Stainless Steel
2	Mass	54.88 Kg
3	Volume	7037167 cubic millimeters
4	Surface area	721309 square millimeters
5	Center of mass	X= 0, Y=400, Z=00
6	Mass Density	7800 Kg/m^3
7	Elastic Modulus	2e+11 N/m^2
8	Yield Strength	172339000 N/m^2
9	Poisson's Ratio	0.28
10	Shear Modulus	7.7e+10 N/m^2
11	Length of Shaft	800mm
12	Outer Diameter	160mm
13	Inner Diameter	120mm
14	Principal axes of inertia and principal moments of inertia taken at the centre of mass $(g \times mm^2)$	Ix = (0.00, 1.00, 0.00) Px = 274449534.22 Iy = (0.00, 0.00, 1.00) Py = 3064686465.43 Iz = (1.00, 0.00, 0.00) Pz = 3064686465.43
15	Moments of inertia taken at the centre of mass and aligned with the output coordinate system $(g \times mm^2)$	Lxx = 3064686465.43
16	Moments of inertia taken at the output coordinate system $(g \times mm^2)$	Ixx = 11847071560.39     Ixy = 0.00     Ixz = 0.00       Iyx = 0.00     Iyy = 274449534.22     Iyz = 0.00       Izx = 0.00     Izy = 0.00     Izz = 1847071560

### **Balls Dimension**

Mass properties of ball.1			
S no.	Specification	Values	
1	Density	7800 kg/m^3	
2	Material	Chrome Stainless Steel	
3	Mass	16.73 g	
4	Radius	16mm	
5	Volume	$2144.66  mm^3$	
6	Surface area	$804.25 \ mm^2$	
7	Centre of mass: (mm)	X = 0.00 Y = 70.00 Z = 0.00	
8	Principal axes of inertia and principal moments of inertia taken at the centre of mass $(g \times mm^2)$	Ix = (1.00, 0.00, 0.00) Px = 428.25 Iy = (0.00, 1.00, 0.00) Py = 428.25 Iz = (0.00, 0.00, 1.00) Pz = 428.25	
9	Moments of inertia taken at the centre of mass and aligned with the output coordinate system $(g \times mm^2)$	Lxx = 428.25 Lxy = 0.00 Lxz = 0.00 Lyx = 0.00 Lyy = 428.25 Lyz = 0.00 Lzx = 0.00Lzy = 0.00Lzz = 428.25	
10	Moments of inertia taken at the output coordinate system $(g \times mm^2)$	Ixx = 82397.17 Ixy = 0.00 Ixz = 0.00 Iyx = 0.00 Iyy = 428.25 Iyz = 0.00 Izx = 0.00 Izy = 0.00 Izz = 82397.17	





# Figure:- Front view of ball Controller Requirement Description

S No.	Properties	value
1	Unit power supply rated voltage	24 VCD (20.4 to 26.4 VCD)
2	Unit power supply current consumption	660mA or less
3	Operating environment	Ambient temp5 to 55°C
4	Ambient operating humidity	10 to 95 %
5	Ambient storage temperature	-25 to +70°C
6	Vibration resistance	Conforms to IEC 60068-2-6. 5 to 8.4 Hz with amplitude of 3.5 mm, 8.4 to 150 Hz, acceleration

7	Shock resistance	of 9.8 m/s <sup>2</sup> 100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)  Conforms to IEC 60068-2-6. 5 to 8.4 Hz with amplitude of 3.5 mm, 8.4 to 150 Hz, acceleration of 9.8 m/s <sup>2</sup> 100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)
8	Applicable standards	EU: EN 61326, RCM, KC Registration, UL
9	How many axis tracking	2
10	In build features	<ul> <li>Universal Motion Controller up to 5 Axes</li> <li>Delta Tau's Pmac2 Technology</li> <li>Powerful Axes Controller CPU</li> <li>Embedded Pc104 Computer</li> <li>Compact Operator Panel and Soft PLC IEC 1131</li> <li>Front panel with a flat screen</li> <li>F-keys and keyboard for easy programming</li> </ul>
11	Hardware interface	<ul> <li>IN/OUT 32 Inputs 12 - 30V, Opto-Isolated sourcing</li> <li>AMP 1 +/10V Axes - Command Signal, AMPENA</li> <li>FLG 1 LIMIT +, LIMIT-,HOME, USER inputs</li> <li>STP Pulse-Direction Interface for Axes 1 - 4</li> <li>ENC1ENC4 4 x RS422 Encoder Input 5V, max 10MHz Frequency</li> <li>ENC 5 / HW1 1 x RS422 Encoder Input 5V, max 10MHz Frequency (for 5th Axes or Hand-Wheel)</li> </ul>